

# DISTRIBUTION FUNCTIONS NOMENCLATURE & DEFINITIONS

①

## DISTRIBUTION FUNCTION

PHASE SPACE DENSITY

$f(\vec{r}, \vec{v})$ . Most often written as  $f(\vec{v})$ .

Usually normalized such that  $\int f(\vec{v}) d^3v = N$  (particle density)

Units of  $f(\vec{r}, \vec{v})$  are  $\frac{1}{\text{cm}^3 (\frac{\text{cm}}{\text{s}})^3}$  (or  $\frac{\text{unitless}}{\text{cm}^3 (\frac{\text{cm}}{\text{s}})^3}$ ) particles. Thus  $dN = f d^3v$

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(Particle) Flux:

$\vec{J} = \int \vec{v} N = \int \vec{v} dN$ . Units:  $\frac{1}{\text{cm}^2 \text{s}}$  (or  $\frac{\# \text{ particles}}{\text{cm}^2 \text{ s}}$ )

↖ fluid velocity, or bulk velocity

$$d\vec{J} = \vec{v} dN = \vec{v} f \cdot d^3v$$

Differential (Particle) Flux: (A)  $\frac{d\vec{J}}{dE}$  units:  $\frac{1}{\text{cm}^2 \text{s KeV}}$  (or  $\frac{\# \text{ particles}}{\text{cm}^2 \text{s KeV}}$ )

→ Differential (Particle) Flux: (B)  $\frac{d\vec{J}}{dE d\Omega}$  units  $\frac{1}{\text{cm}^2 \text{s KeV str}}$  (or  $\frac{\# \text{ particles}}{\text{cm}^2 \text{s KeV str}}$ )

↑ steradian

③

Energy Flux:

$\vec{Q} = \int \vec{v} N \cdot E$  Units:  $\frac{\text{keV}}{\text{cm}^3 (\text{s/cm})} = \frac{\text{keV}}{\text{cm}^2 \cdot \text{s}}$

$$d\vec{Q} = \vec{v} dN \cdot E = \vec{v} E f d^3v$$

Differential Energy Flux: (A)  $\frac{d\vec{Q}}{dE}$  units:  $\frac{\text{keV}}{\text{cm}^2 \cdot \text{s} \cdot \text{KeV}}$

Differential Energy Flux: (B)  $\frac{d\vec{Q}}{dE d\Omega}$  units:  $\frac{\text{keV}}{\text{cm}^2 \text{s KeV str}}$

distribution function  
From (eg. Maxwellian) to counts

$$f \text{ (cm}^6/\text{s)}^{-1}$$

$$f(\vec{r}, \vec{v}) = \frac{N}{\sqrt{\pi^3} v_{th}^3} e^{-\frac{(\vec{v} - \vec{v}_0)^2}{v_{th}^2}} \quad v_{th} = \sqrt{\frac{2kT}{m}}$$

Note:  $\int_{-\infty}^{\infty} e^{-ax^2} dx = \sqrt{\frac{\pi}{a}}$  Such that  $\int f d^3v = N$

Given  $N, \vec{v}_0, T$  can get  $f$  vs.  $v, \theta, \phi$   
and  $f$  vs.  $E, \theta, \phi$

Diff Flux  $\frac{d\vec{J}}{dE d\Omega} \text{ (cm}^2 \text{ s Kev str)}^{-1}$

$$d\vec{J} = \vec{v} f(\vec{v}) d^3v$$

$$d\vec{J} = \vec{v} f(\vec{E}) d^3v = \vec{v} f(\vec{E}) v^2 dv d\Omega = v^3 \hat{v} f(\vec{E}) d\Omega dv = \\ = v^2 \hat{v} f(\vec{E}) d\Omega d\left(\frac{v^2}{2}\right) \\ = \frac{2(v^2)}{m^2} \hat{v} f(\vec{E}) d\Omega d\left(\frac{mv^2}{2}\right) = \frac{2}{m^2} E \hat{v} f(\vec{E}) d\Omega dE$$

$$\frac{d\vec{J}}{dE d\Omega} = \frac{2v}{m^2} E f(\vec{E}) = \frac{2}{m^2} \vec{E} f(\vec{E}) \quad \vec{E} = (E, \theta, \phi)$$

Given  $N, \vec{v}_0, T$  can get  $dJ/dE d\Omega$  vs.  $E, \theta, \phi$

Diff. Energy Flux  $\frac{d\vec{Q}}{dE d\Omega} \text{ (Kev cm}^2 \text{ s Kev str)}^{-1}$

$$d\vec{Q} = \vec{v} E f(\vec{v}) d^3v = \vec{v} E f(\vec{E}) v^2 dv d\Omega = v \cdot \vec{E} f(\vec{E}) v d\left(\frac{v^2}{2}\right) d\Omega = \\ = 2 \frac{v^2}{2} \vec{E} f(\vec{E}) d\left(\frac{v^2}{2}\right) d\Omega = \frac{2}{m^2} E \vec{E} f(\vec{E}) dE d\Omega$$

$$\frac{d\vec{Q}}{dE d\Omega} = \frac{2}{m^2} E \vec{E} f(\vec{E}) \quad \text{or} \quad = E \cdot \left( \frac{d\vec{J}}{dE d\Omega} \right)$$

#### ④ Particle Count Rate

$$\vec{R} \left( \overset{\text{units}}{s^{-1}} \right) = \frac{d\bar{J}}{dE d\Omega} * G * E * \varepsilon = \frac{d\bar{a}}{dE d\Omega} \cdot G \cdot \varepsilon$$

⇒ Geometric factor for electrostatic Analyzers

$$G = \left[ \begin{array}{ccc} \text{Area} & \cdot & \text{Solid Angle} & \cdot & \text{Bin Energy width} & / & \text{Energy of channel} \\ \text{cm}^2 & & \text{sr} & & \text{eV} & & \text{eV} \end{array} \right]$$

$$\text{units: cm}^2 \text{ sr eV} / \text{eV}$$

Multiplied by units of  $\frac{d\bar{a}}{dE d\Omega} \left( \frac{\text{eV}}{\text{cm}^2 \text{ sr eV}} \right)$  results in (#/s)

G is a function of energy channel, as well as detector direction. Thus  $G(E, \theta, \varphi)$  depends on specifics of instrument.

→  $\Delta E =$  energy bandwidth

For electrostatic analyzers the inherent energy resolution

$$\Delta E \text{ is proportional to the energy: } E = \frac{qV}{2} \cdot \frac{R}{\Delta}$$

where  $\Delta$  is gap,  $R$  is radius. This is because

$$\Delta E = qV/2 \cdot \Delta R / \Delta \text{ and } \frac{\Delta E}{E} = \frac{\Delta}{R} = \frac{1}{K}, \text{ where } K \text{ is the analyzer constant. So } \Delta E/E \text{ is constant and is part of the geometric factor of the instrument.}$$

→  $\varepsilon =$  detection efficiency. This is the number of counts registered for a given number of particles that hit the detector. This gets us from # particles/s to # counts/s. Typical values for electrostatic analyzers is 0.6-0.7

⑤ Particle Counts.

$$\bar{C} \text{ (unitless)} = \bar{R} * \tau$$

$\tau$  is the measurement interval (seconds)

Note:  $\frac{\bar{R}}{G E} = \frac{d\bar{a}}{dE d\Omega} = E \frac{d\bar{J}}{dE d\Omega} \propto E^2 \cdot f$

↑  
diff. energy flux

↑  
diff. flux

↑  
distr. function

UNITS:  $\bar{R} \text{ (# counts/s)}$ ;  $\frac{d\bar{a}}{dE d\Omega} \left( \frac{ev}{ev \text{ cm}^2 \text{ s str}} \right)$ ;  $G \left( \text{cm}^2 \text{ str } ev/ev \right)$

NOTE: counts/s are dead time corrected

This dead-time correction is necessary before using the above equation.

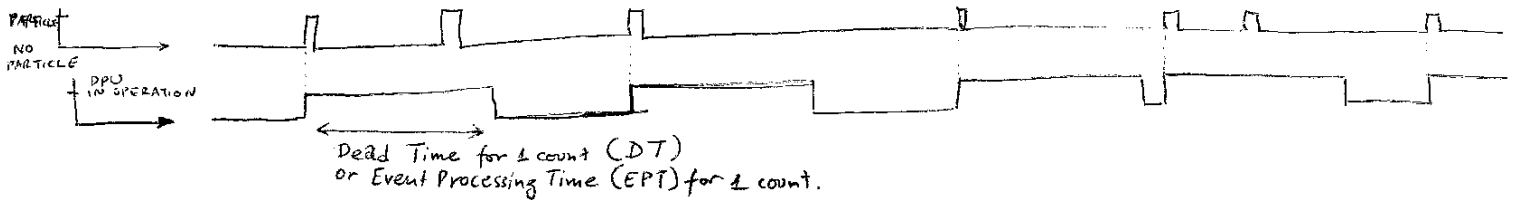
Counts "C" is # counts per sample

$$C = R * AT \text{ , where AT is accumulation time}$$

## DEAD TIME CORRECTIONS

In addition to geometric factor, detector efficiency and energy bandwidth we need to apply a dead time correction to the counts measured to get the counts in the plasma.

The dead time results from the processing that needs to take place once an event has been registered, as the DPP is occupied.



Thus the total dead time is a function of the number of counts.

Total DT =  $C_m \cdot EPT$ . Live time (LT) is the time the detector was in operation.  $LT = AT - DT$ , where AT is the accumulation interval, or Accumulation time. EPT = event processing time for 1 count.

Then the actual count rate is:  $R_{\text{real}} = \frac{C_m}{LT} = \frac{C_m}{AT - DT} \Rightarrow$

$$\Rightarrow R_{\text{real}} = \frac{C_m}{AT - C_m EPT} = \frac{C_m / AT}{1 - C_m \frac{EPT}{AT}} = \frac{R_{\text{measured}}}{1 - \underbrace{R_{\text{measured}} \cdot EPT}_{\text{always } < 1}}$$

always  $< 1$   
: you cannot have in a given  
AT more particles than EPT's

Thus dead time correction consists of dividing the measured rate by the quantity  $(1 - R_{\text{measured}} \cdot EPT)$ .

NOTE:  $\frac{1}{EPT} = \text{max count rate}$  (because  $\frac{1}{EPT} = \frac{AT}{EPT} \frac{1}{AT} = \frac{\text{max \# of counts}}{AT} = \text{max count rate}$ )

FURTHER READING: Curtis et al. "On board data analysis techniques..." Rev. Sci. Instr. 60, 374, 1989

For on-board processing on AMPTE/IRM the formula given on page 374 of D. Curtis's paper can be understood as follows:  
For each sample

$$R_{\text{real}} = \frac{C_m}{AT - C_m \text{EPT}} = \frac{C_m/\text{EPT}}{\frac{AT}{\text{EPT}} - C_m}$$

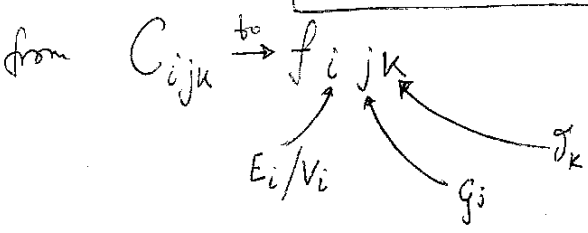
\* The  $C_m/\text{EPT}$  in the numerator can be normalized away and re-entered on the ground. Thus  $CR_n(\odot)$  represents the normalized count rate =  $C_m/\text{EPT}$  in units that maximize the dynamical range of the on-board computations

\*  $\left(\frac{AT}{\text{EPT}}\right)$  is the accumulation time over a single energy measurement divided by the event processing time (in paper <sup>EPT is</sup> referred to as "dead time") and represents the maximum number of counts (denoted as  $CR_{\text{max}}$  in paper)

\*  $C_m$  is the measured counts referred to as  $CR_i$  in the paper.

Thus  $R_{\text{real}} \approx \frac{CR_n}{CR_{\text{max}} - CR_i}$

# FROM COUNTS TO DISTRIBUTION FUNCTION



IRM-SPECIFIC

Assuming  $\frac{\Delta E}{E} = \text{constant} = \frac{2\Delta V}{V}$

AT = Accumulation time =  $\frac{\text{Spin Period} \cdot 4}{16 \times 30} = \frac{4}{512 \times 30}$

EPT = Event Processing Time  $\sim 10^{-6}$  s

$R_m$  = measured count rate =  $\frac{C_m}{AT}$

$C_m$  = measured counts per sample

$R_r$  = real count rate (dead time corrected)

$G$  = Geometric factor ( $\theta$ )

$\Delta E$  = Energy bandwidth ( $E$ )

$\epsilon$  = Efficiency ( $E, \theta$ )

$$R_m = \frac{C_m}{AT}$$

$$R_r = \frac{R_m}{1 - R_m \cdot EPT}$$

$$R_r = \left( \frac{dJ}{dE d\Omega} \right) G \cdot \epsilon \cdot E = \frac{2}{m^2} E \cdot f \cdot G \cdot \frac{\Delta E}{E} \cdot E \cdot \epsilon = 2 \frac{E^2}{m^2} f \cdot G \cdot \frac{2\Delta V}{V} \cdot \epsilon = 4 f G \frac{\Delta V}{V} \epsilon$$

According to p.3 =  $\frac{2}{m^2} \dot{E} f(\dot{E})$

$$\Rightarrow f(\dot{v}) = \frac{C_m/AT}{1 - \frac{C_m}{AT} \cdot EPT} \cdot \frac{1}{V^4} \cdot \frac{1}{\left[ G \left( \frac{\Delta V}{V} \right) \epsilon \right]}$$

Discrete Steps:

$$f_{ijk} = \frac{(C_{ijk}/AT)}{1 - \frac{C_{ijk}}{AT} \cdot EPT} \cdot \frac{1}{V_i^4} \cdot \frac{1}{G_k \left( \frac{\Delta V}{V} \right) \epsilon_{ik}}$$

$\langle V_i^4 \rangle$        $\langle \frac{\Delta V}{V} \rangle$

$$f_{ijk} = \frac{C_{ijk}/AT}{1 - \frac{C_{ijk}}{AT} \cdot EPT} \cdot \frac{1}{\frac{9E^2}{m^2}} \cdot \frac{1}{G_k \cdot \text{eff} \cdot \left( \frac{\Delta E}{E} \right)}$$